

MS5: STEEPEST DESCENTS - INTRO

Note Title

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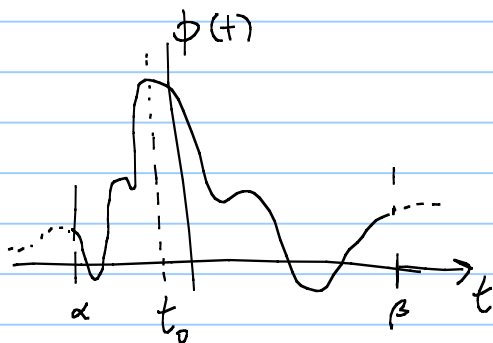
In these notes we will discuss the central core of methods used to treat the asymptotic expansion of integrals - they are also used for understanding differential equations. These methods go under the general label of "STEEPEST DESCENT" methods. Two apparent special cases of steepest descent are Laplace's method & the method of stationary phase (they are not quite special cases, because their realms of applicability are slightly different).

These notes are rather introductory - they need to be supplemented by a more thorough analysis, as well as a thorough discussion of examples.

If one is not too interested in rigor, the method is actually fairly straightforward. In its simplest form it is just a generalisation of the standard Gaussian integral. Consider an integral of the form we already discussed in eqn (B.7) of "MS4: Asymptotic Analysis", viz., an integral

$$S(x) = \int_{\alpha}^{\beta} dt e^{x\phi(t)} f(t) \quad (A.1)$$

where $f(t)$ & $\phi(t)$ are real, and we assume $x \gg 1$. In our previous discussion of this we integrated by parts, but as we saw this doesn't always work.



The basic idea is evident if we consider the behaviour of $\phi(t)$ between the limits. There will be some largest value of $\phi(t)$ for $t = t_0$, and we then make the expansion

$$\phi(t) \sim \phi_0 + \frac{\phi_0''}{2} (t-t_0)^2 + \dots + \frac{\phi_0^{(n)}}{n!} (t-t_0)^n + \dots \quad (A.2)$$

where $\phi_0 \equiv \phi(t_0)$ and $\phi_0^{(n)} \equiv \left. \frac{d^n \phi}{dt^n} \right|_{t=t_0}$

Now we can do the integral quite easily if we assume that $f(t)$ is sufficiently slowly varying around $t = t_0$ compared to the exponentially rapidly varying $e^{x\phi(t)}$; if x is large enough this will always be the case. We then have

$$S(x) \sim \int_a^b dt e^{x(\phi_0 + \frac{\phi_0''}{2}(t-t_0)^2)} f(t)$$

$$\xrightarrow{x \gg 1} f_0 e^{x\phi_0} \int_{-\infty}^{\infty} dt e^{x \frac{\phi_0''}{2} (t-t_0)^2}$$

$$= \left(\frac{2}{-\phi_0'' x} \right)^{1/2} f_0 e^{x\phi_0} \int_{-\infty}^{\infty} dy e^{-y^2}$$

$$= \left(\frac{2\pi}{-x\phi_0''} \right)^{1/2} f_0 e^{x\phi_0} \quad (A.3)$$

where $f_0 = f(t_0)$, and $y^2 = x \frac{\phi_0''}{2} (t-t_0)^2$. Integrals of this form are known as Laplace-type integrals (the method being called Laplace's method).

If $\phi_0'' = 0$, we continue on to the first non-zero derivative. If this is $\phi_0^{(n)}$, then a repeat of the above calculation gives

$$S(x) \sim \int_a^b dt e^{x(\phi_0 + \frac{\phi_0^{(n)}}{n!} (t-t_0)^n)}$$

$$\xrightarrow{x \gg 1} \frac{2}{n} \Gamma\left(\frac{1}{n}\right) \left(\frac{n!}{-x\phi_0^{(n)}} \right)^{1/n} f_0 e^{x\phi_0} \quad (A.4)$$

where we use $\int_{-\infty}^{\infty} dy e^{-y^n} = \frac{2}{n} \Gamma\left(\frac{1}{n}\right)$.

Example: The best-known example of this is the integral leading to the Γ -function itself. Consider

$$\Gamma(1+x) = \int_0^{\infty} dt e^{-t} t^x \equiv \int_0^{\infty} dt e^{x \ln t - t} \quad (A.5)$$

which has a maximum at $t = t_0 = x$.

If we now expand about $t = x$, we have

$$\begin{aligned}
 \Gamma(1+x) &\xrightarrow{x \gg 1} \int_0^{\infty} dt e^{x \ln t - x} e^{-\frac{1}{2x}(t-x)^2} \\
 &\sim e^{x \ln x - x} \int_{-\infty}^{\infty} dt e^{-\frac{1}{2x}(t-x)^2} \\
 &= (2\pi x)^{\frac{1}{2}} x^x e^{-x} \equiv (2\pi x)^{\frac{1}{2}} \left(\frac{x}{e}\right)^x \quad (A.6)
 \end{aligned}$$

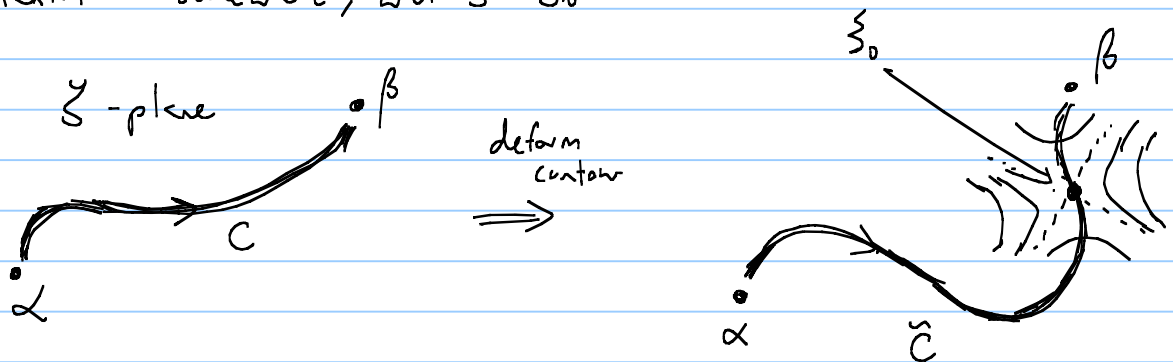
which is nothing but Stirling's formula. Note that this is just the first term in the asymptotic expansion. In fact one finds that

$$\Gamma(1+x) \sim (2\pi x)^{\frac{1}{2}} \left(\frac{x}{e}\right)^x \left[1 + \frac{1}{12x} + \frac{1}{288x^2} + \dots\right] \quad (A.7)$$

Now this is clearly a method that can easily be generalised. Consider the integral

$$S(z) = \int_C d\xi e^{z\phi(\xi)} f(\xi) \quad (A.8)$$

along some contour. Now we assume that $|\phi(\xi)|$ has a maximum somewhere, when $\xi = \xi_0$



We then realise that the point $\xi_0 = u_0 + i v_0$ must be a saddle point of the function $\phi(\xi)$ at ξ_0 , because of the Cauchy-Riemann eqns. This means that the contours of constant $\text{Re } \phi(\xi)$ near ξ_0 must look like what is shown on the right picture above, and at the saddle point

$$\frac{\partial \phi}{\partial u} = \frac{\partial \phi}{\partial v} = 0 \quad \left| \phi = \phi(\xi_0) = \phi_0 \right. \quad (A.9)$$

Here $\partial\phi/\partial u = 0$ because we are at a maximum of ϕ , and then $\partial\phi/\partial v = 0$ by Cauchy-Riemann.

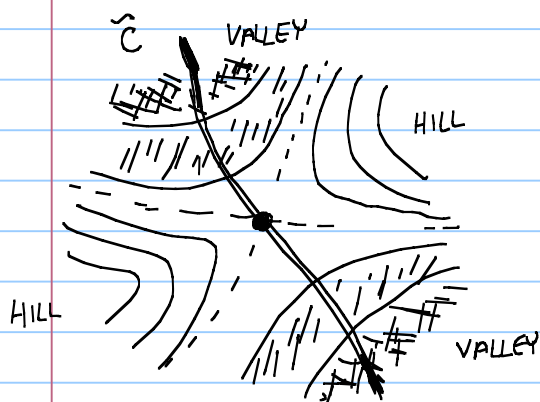
Provided we do not cross any singularities (poles, branch cuts) in $\phi(z)$, we can then deform the contour C to \tilde{C} as shown above so that it follows a path, as z_0 is approached, such that $\text{Im } \phi(z) = \text{const}$ along this path, i.e., the PHASE of the function $\phi(z)$ does not change as we go along the path. We can then write

$$\phi(z) = \gamma(z) + i\chi(z) \rightarrow \gamma(z) + i\chi_0 \quad (\text{A.10})$$

$$\begin{aligned} \text{so that } S(z) &= \int_{\tilde{C}} dz e^{z\phi(z)} f(z) \\ &\rightarrow e^{iz\chi_0} \int_{\tilde{C}} dz f(z) e^{z\gamma(z)} \quad (\text{A.11}) \end{aligned}$$

Now we see that the exponent is easy to treat - basically this integral is now of the Laplace type we saw before.

The method is called the method of steepest descents because if we hold $\chi(z) \rightarrow \chi_0 = \text{const}$, then the exponent $\gamma(z)$ varies as fast as possible along the contour \tilde{C} .



This is obvious from the close-up of the region round the saddle point at z_0 ; lines of steepest descent are perpendicular to contours of constant $\gamma(z)$, and are thus lines of constant $\chi(z)$. To see this formally we just write the Cauchy-Riemann eqns

$$\left. \begin{aligned} \frac{\partial \gamma}{\partial u} \frac{\partial \chi}{\partial u} + \frac{\partial \gamma}{\partial v} \frac{\partial \chi}{\partial v} &= 0 \end{aligned} \right\} (\text{A.12})$$

$$\text{so } \nabla \gamma \cdot \nabla \chi = 0$$

and this implies they are perpendicular.

Let's look in more detail at this saddle point region. It is useful to expand round $\xi = \xi_0$ in the form

$$\xi - \xi_0 = \rho e^{i\theta} \quad \left. \frac{\partial^2 \phi(\xi)}{\partial \xi^2} \right|_{\xi = \xi_0} = R e^{i\psi} \quad (\text{A.13})$$

and also

$$\phi(\xi) = \alpha + i\beta \quad (\text{A.14})$$

We know that in the saddle point region

$$\phi(\xi) - \phi(\xi_0) \sim \frac{1}{2} \left. \frac{\partial^2 \phi}{\partial \xi^2} \right|_{\xi = \xi_0} (\xi - \xi_0)^2 \quad (\text{A.15})$$

ie

$$(\alpha - \alpha_0) + i(\beta - \beta_0) \sim \frac{1}{2} R \rho^2 e^{i(\psi + 2\theta)} \quad (\text{A.16})$$

Now we can see that the direction of steepest descent (ie, the angles ϕ along which we get steepest descent) are given by

$$\cos(\psi + 2\theta) = -1 \quad (\text{A.17})$$

so that $\psi + 2\theta = \pi, 3\pi$, and so we have

$$\text{steepest descent lines:} \quad \theta = \begin{cases} \frac{\pi}{2} - \psi/2 \\ \frac{3\pi}{2} - \psi/2 \end{cases} \quad (\text{A.18})$$

$$\text{steepest ascent lines:} \quad \theta = \begin{cases} -\psi/2 \\ \frac{\pi}{2} - \psi/2 \end{cases} \quad (\text{A.19})$$

It then follows immediately that we can write the original integral in the form

$$S(z) = \int_{\bar{c}} d\xi e^{z\phi(\xi)} f(\xi)$$

$$\sim e^{z\phi_0} f_0 e^{i\theta} \int_{-\infty}^{\infty} d\rho e^{-\frac{z}{2} R \rho^2} = \left(\frac{2\pi}{zR} \right)^{1/2} e^{i\theta} f_0 e^{z\phi_0} \quad (\text{A.20})$$

$$\text{where } f_0 = f(\xi_0) \\ \phi_0 = \phi(\xi_0)$$

and θ is one of the 2 angles in (A.18) (which one we take depends on which direction we follow the path).

Example: Let's look at the Γ -function again, but this time for complex argument. Then we define.

$$\Gamma(1+z) = \int_0^{\infty} d\xi e^{z \ln \xi - \xi} \quad (\text{A.21})$$

$$\text{i.e., if we write } \Gamma(1+z) = \int_0^{\infty} d\xi f(\xi) e^{z\phi(\xi)}$$

$$\text{then } \phi(\xi) = \left(\ln \xi - \xi/z \right) \quad (\text{A.22})$$

It then follows that the saddle point is located at

$$\frac{\partial \phi}{\partial \xi} = 0 \quad \text{when } \xi = \xi_0 = z \quad (\text{A.23})$$

$$\text{at which point we have } \left. \frac{\partial^2 \phi}{\partial \xi^2} \right|_{\xi=z} = -\frac{1}{z^2} \quad (\text{A.24})$$

$$\text{If we write } z = x + iy = z_0 e^{i\theta} \quad (\text{A.25})$$

then we easily find that the directions of steepest descent are along the directions

$$\theta = \begin{cases} \theta/2 \\ \theta/2 + \pi \end{cases} \quad (\text{A.26})$$

and we get for the steepest descent result for $\Gamma(1+z)$ that

$$\left. \begin{aligned} \Gamma(1+z) &\sim (2\pi z_0)^{1/2} e^{i\theta/2} e^{z \ln z - z} \\ &= (2\pi)^{1/2} z^{z+1/2} e^{-z} \end{aligned} \right\} \quad (\text{A.27})$$