

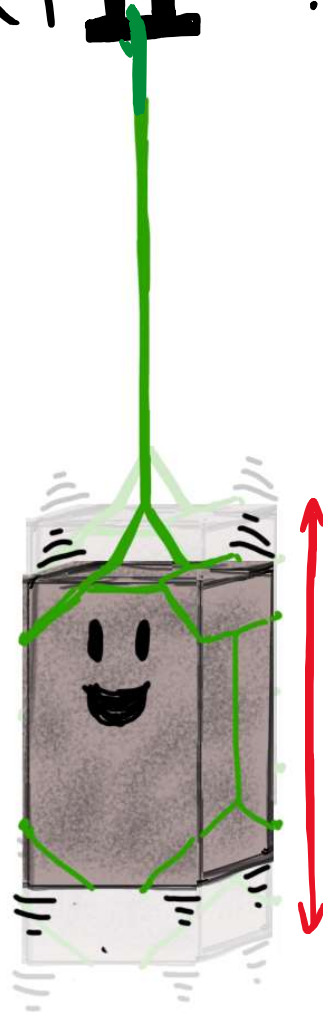
Office hours today: 4-5pm (Zoom), 8-9pm (Zoom)

Midterm Q&A: 5-7pm (Zoom link on main Canvas page)

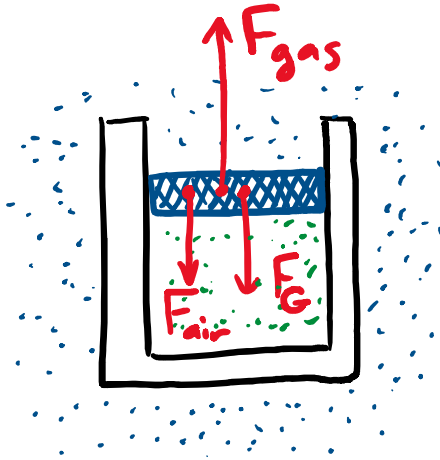
Learning Goals for Today:

- To define what is meant by mechanical equilibrium
- To explain the idea of restoring forces for a system perturbed from a stable mechanical equilibrium situation and how these lead to periodic oscillations
- To explain why Hooke's law applies in general for mechanical systems that are slightly displaced from a stable equilibrium configuration
- To mathematically describe the displacement vs time for mechanical system oscillating under the influence of restoring forces obeying Hooke's law
- To relate the parameters appearing in the sinusoidal function describing an oscillation to the physical properties of the oscillation, including the period, frequency, amplitude, and phase

PHYSICS 157 PART **II** : OSCILLATIONS & WAVES



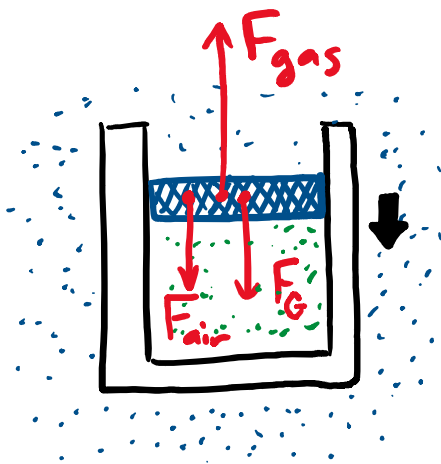
MECHANICAL EQUILIBRIUM: occurs when forces (and torques) on each part of the system add to zero



example: $\vec{F}_{\text{gas}} + \vec{F}_{\text{gravity}} + \vec{F}_{\text{air}} = 0$

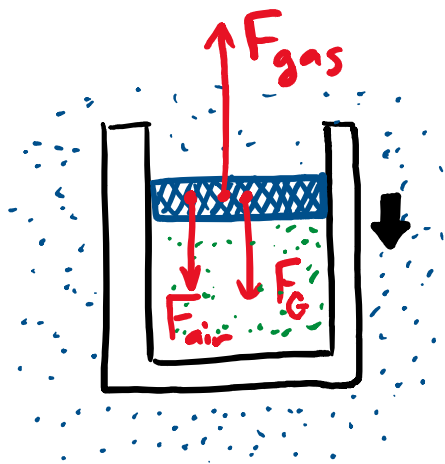
- piston is in equilibrium

What happens to the forces if we move the piston downward a little (assume the cylinder is insulated)?



- A) $|F_{\text{gas}}|$ increases a little while the other forces remain the same.
- B) $|F_{\text{gas}}|$ increases a little and $|F_{\text{air}}|$ increases to compensate.
- C) $|F_{\text{gas}}|$ decreases a little and the other forces remain the same.
- D) $|F_{\text{gas}}|$ decreases a little and $|F_{\text{air}}|$ decreases to compensate.
- E) Nothing: all forces remain the same.

What happens to the forces if we move the piston downward a little (assume the cylinder is insulated)?



Adiabatic compression:

$$PV^\gamma = \text{const}$$

$V \downarrow$ so $P \uparrow$

so $F_{\text{air}} \uparrow$

A) $|F_{\text{gas}}|$ increases a little while the other forces remain the same.

B) $|F_{\text{gas}}|$ increases a little and $|F_{\text{air}}|$ increases to compensate.

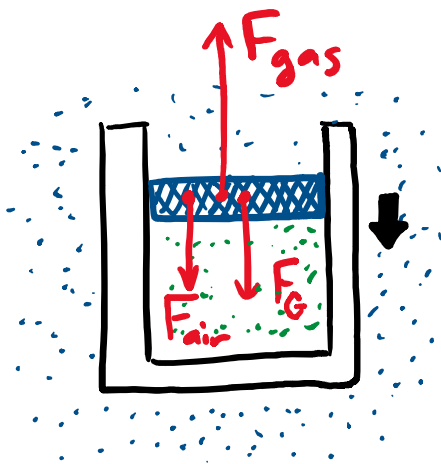
C) $|F_{\text{gas}}|$ decreases a little and the other forces remain the same.

D) $|F_{\text{gas}}|$ decreases a little and $|F_{\text{air}}|$ decreases to compensate.

E) Nothing: all forces remain the same.

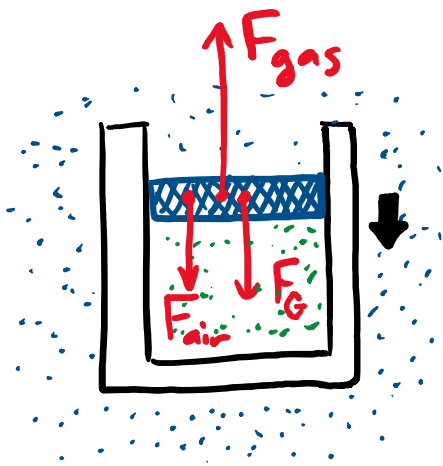
gravity & outside air pressure remain constant

What happens to the forces if we move the piston upward a little (assume the cylinder is insulated)?



- A) $|F_{\text{gas}}|$ increases a little while the other forces remain the same.
- B) $|F_{\text{gas}}|$ increases a little and $|F_{\text{air}}|$ increases to compensate.
- C) $|F_{\text{gas}}|$ decreases a little and the other forces remain the same.
- D) $|F_{\text{gas}}|$ decreases a little and $|F_{\text{air}}|$ decreases to compensate.
- E) Nothing: all forces remain the same.

What happens to the forces if we move the piston upward a little (assume the cylinder is insulated)?



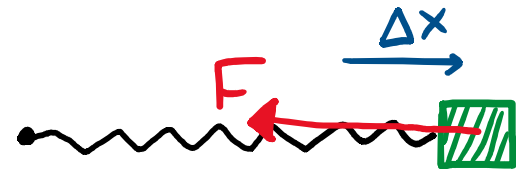
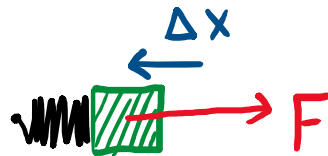
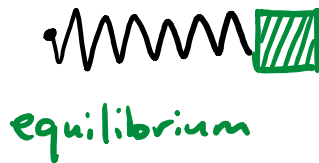
Adiabatic expansion

$P \downarrow$ so $|F_{\text{gas}}| \downarrow$

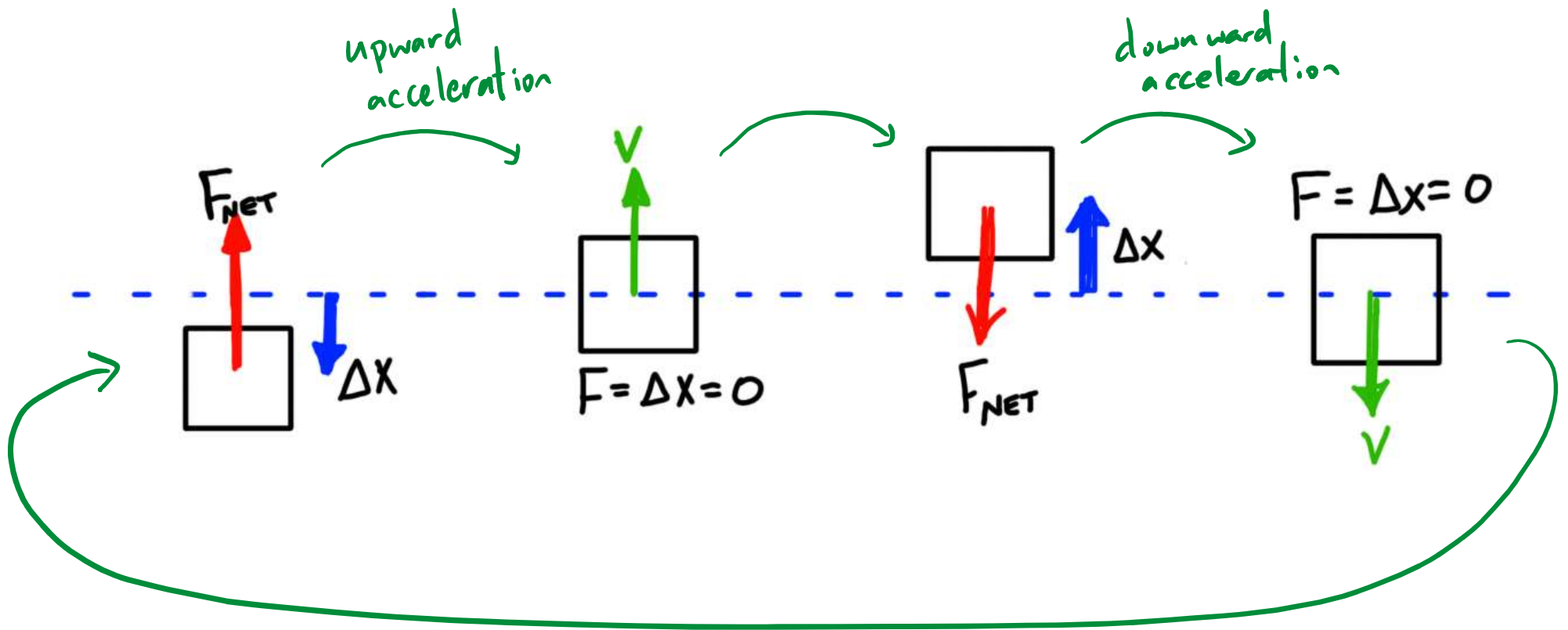
- A) $|F_{\text{gas}}|$ increases a little while the other forces remain the same.
- B) $|F_{\text{gas}}|$ increases a little and $|F_{\text{air}}|$ increases to compensate.
- C) $|F_{\text{gas}}|$ decreases a little and the other forces remain the same.
- D) $|F_{\text{gas}}|$ decreases a little and $|F_{\text{air}}|$ decreases to compensate.
- E) Nothing: all forces remain the same.

RESTORING FORCES: For a STABLE equilibrium configuration, a displacement in one direction leads to a net force in the other direction.

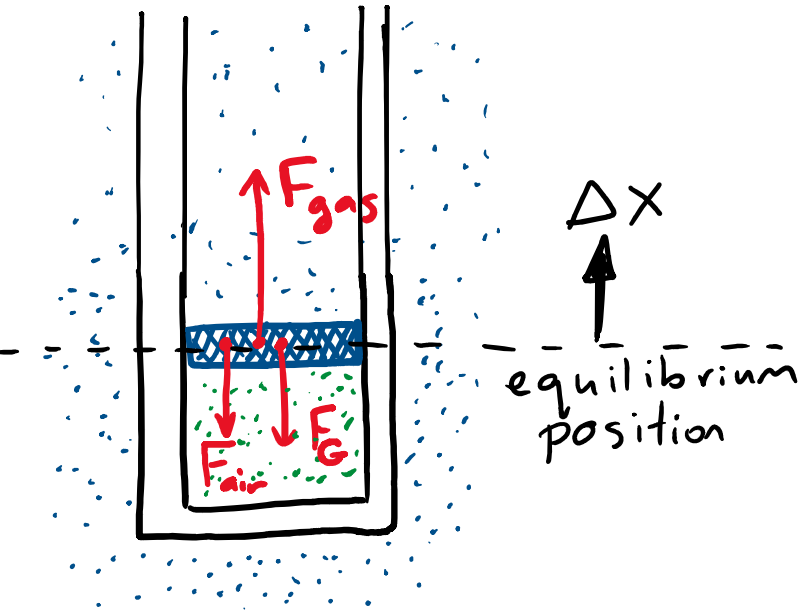
e.g.



This leads to OSCILLATIONS = periodic motion



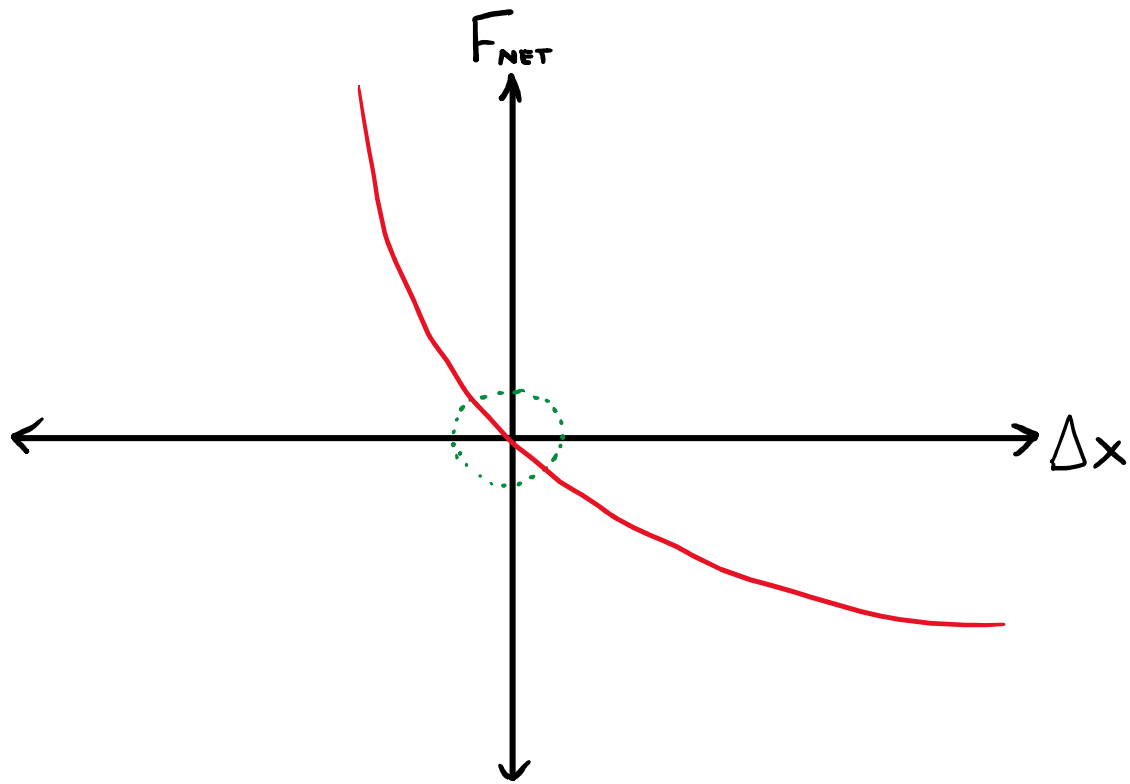
Demo



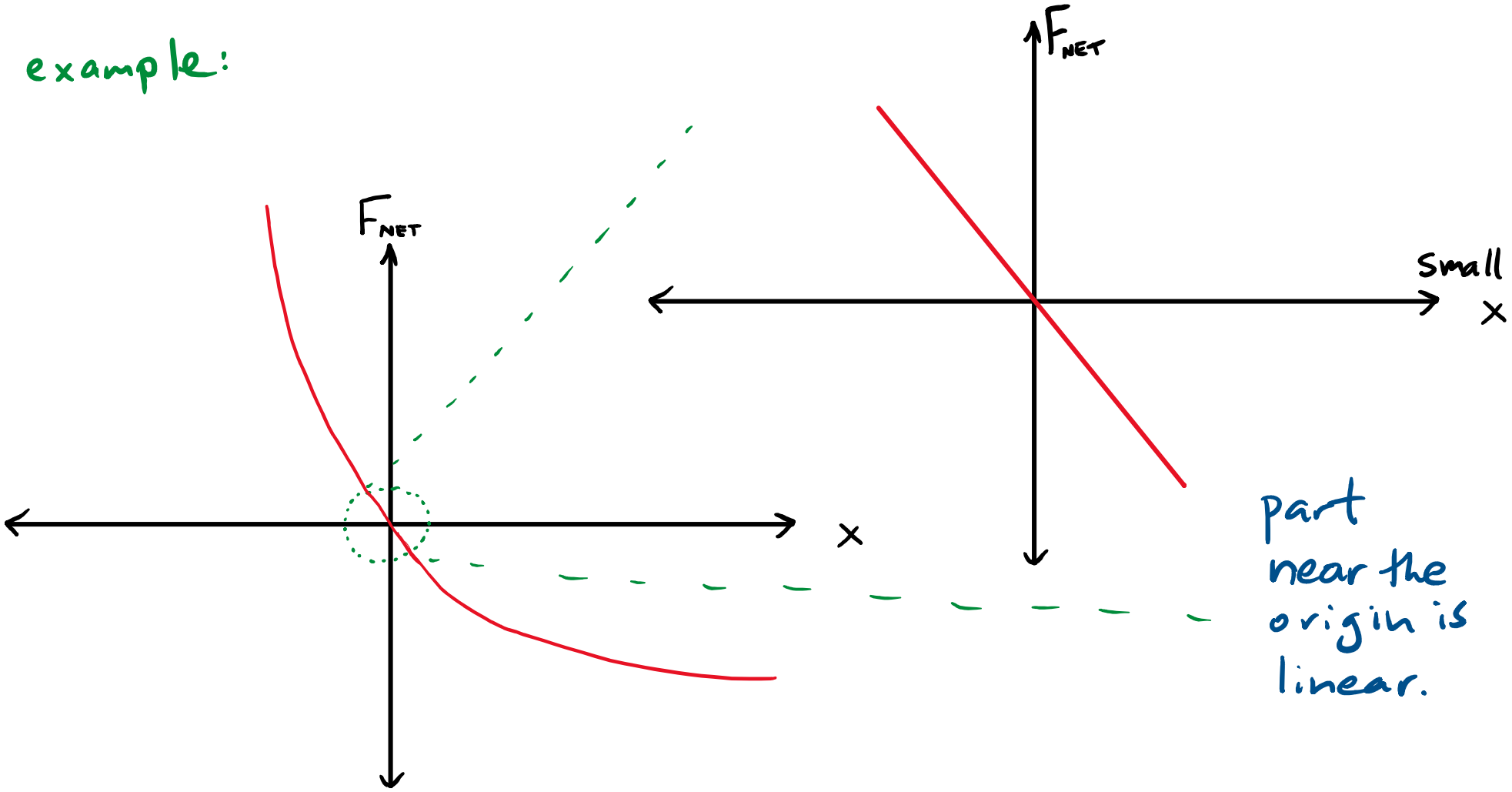
Exercise: For the system shown, sketch a graph of the net upward force on the piston as a function of the displacement Δx from the equilibrium position.

EXTRA: what does your graph look like if you zoom in to the region of small Δx . Can you write down an equation that describes F vs Δx in this region?

example:

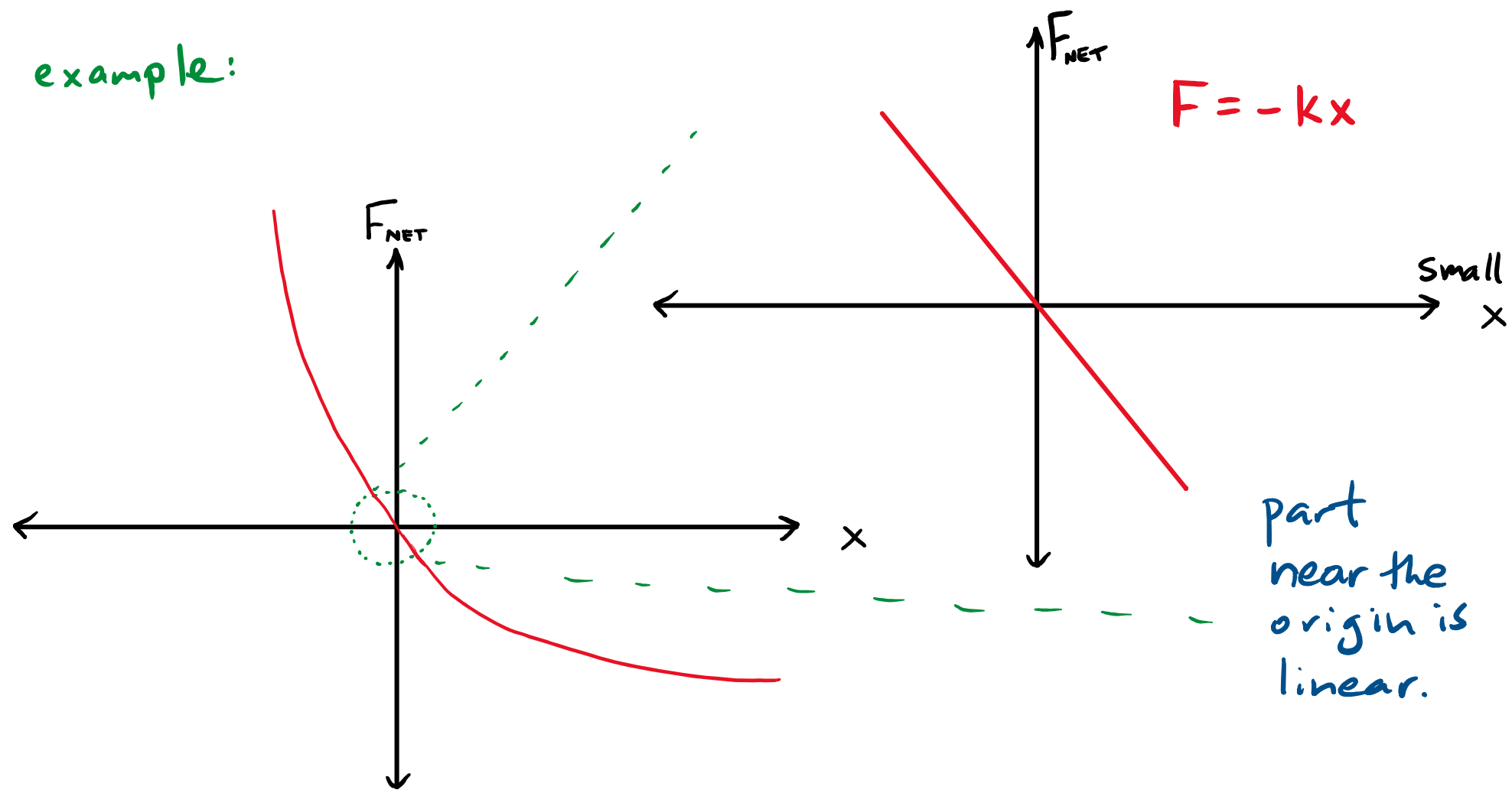


example:



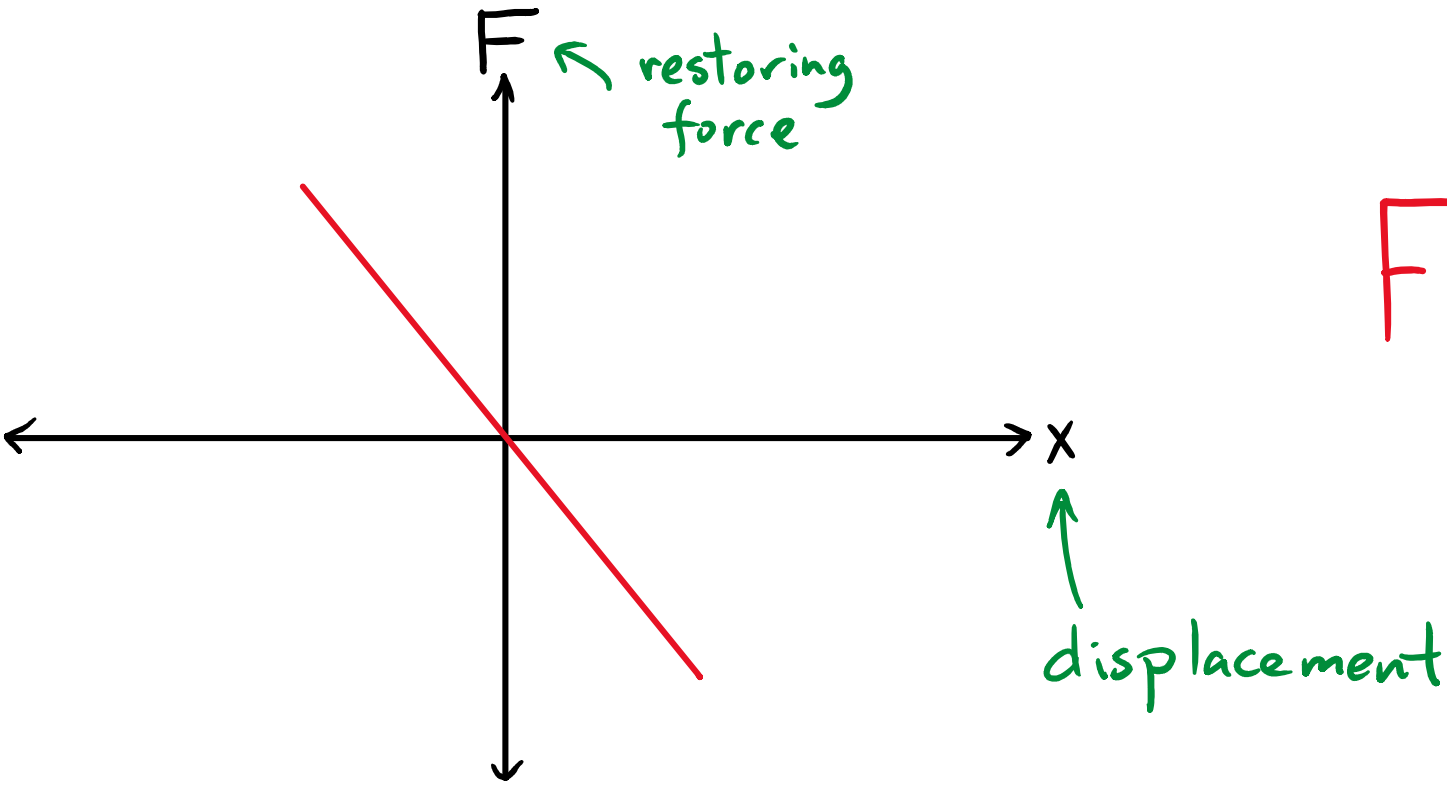
part near the origin is linear.

example:



part near the origin is linear.

HOOKE'S LAW: Applies to almost any system perturbed a small amount from stable equilibrium

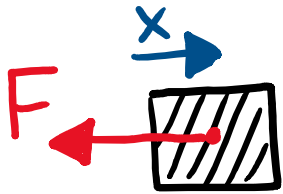


$$F = -kx$$

exact for "ideal spring"

Oscillations with Hooke's Law:

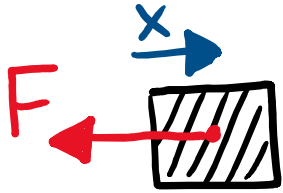
$$\text{Newton: } a = \frac{F}{m}$$



$$F = -kx$$

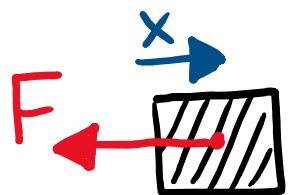
Oscillations with Hooke's Law:

$$\text{Newton: } a = \frac{F}{m} = -\frac{k}{m} \cdot x$$



$$F = -kx$$

Oscillations with Hooke's Law:

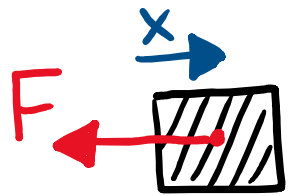


$$F = -kx$$

$$\text{Newton: } a = \frac{F}{m} = -\frac{k}{m}x$$

$$\frac{dv}{dt} = -\frac{k}{m}x$$

Oscillations with Hooke's Law:



$$F = -kx$$

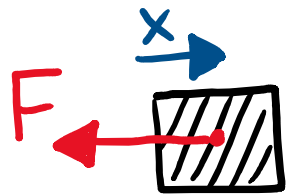
Newton: $a = \frac{F}{m} = -\frac{k}{m}x$

$$\frac{dv}{dt} = -\frac{k}{m}x$$

$$\frac{dx}{dt} = v$$

We can predict how velocity and position change with time.

Oscillations with Hooke's Law:



$$F = -kx$$

$$\text{Newton: } a = \frac{F}{m} = -\frac{k}{m}x$$

$$\frac{dv}{dt} = -\frac{k}{m}x$$

$$\frac{dx}{dt} = v$$

We can predict how velocity and position change with time.

$$\text{Solution is } x(t) = A \cos(\omega t + \phi) \text{ with } \omega = \sqrt{\frac{k}{m}}$$

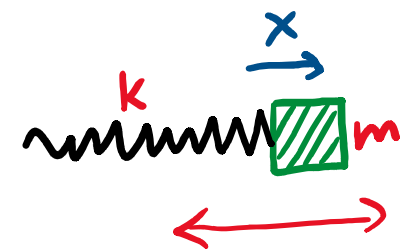
SIMPLE HARMONIC MOTION

$$x(t) = A \cos(\omega t + \phi)$$

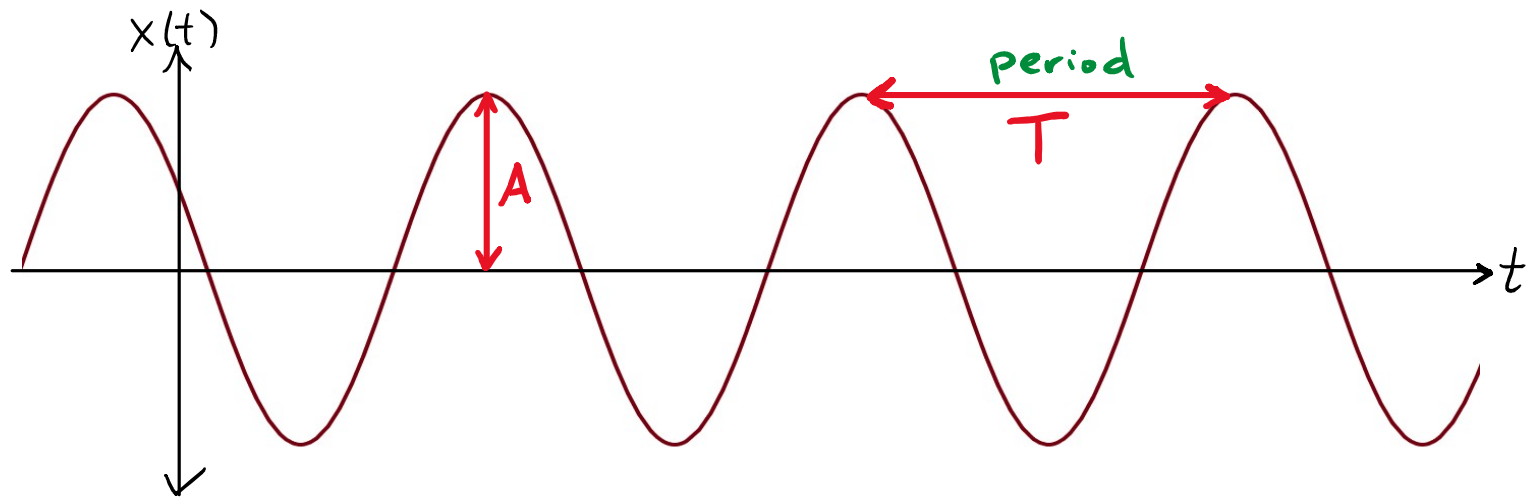
Amplitude

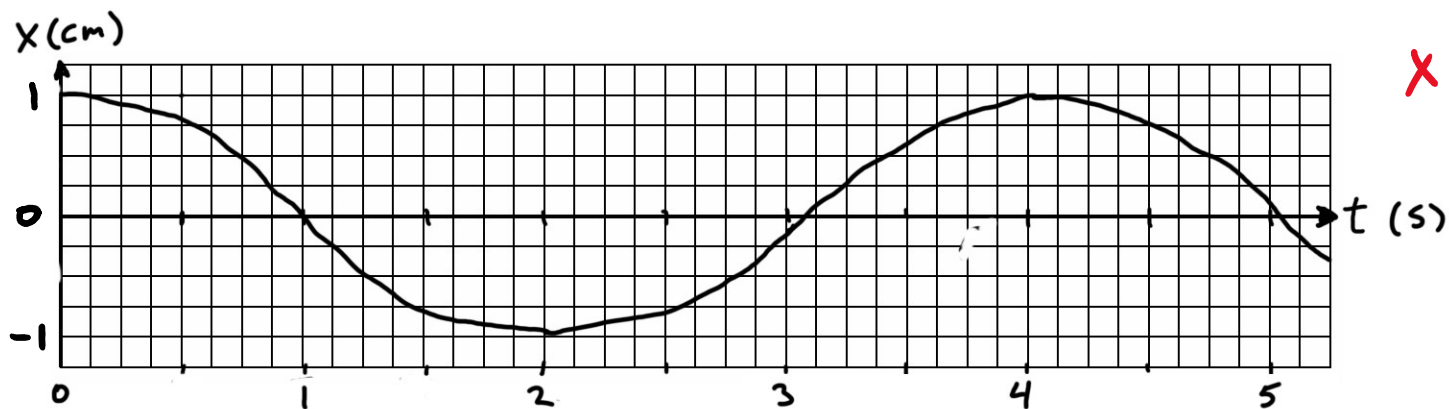
angular
frequency

phase



$$\omega = \sqrt{\frac{k}{m}}$$



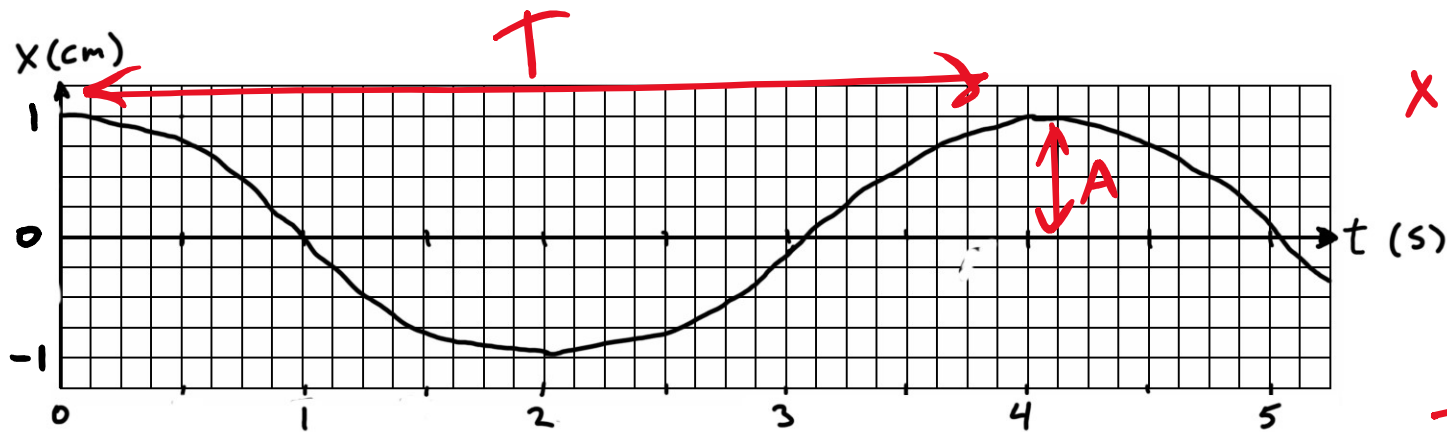


$$x(t) = A \cos(\omega t + \phi)$$

A plot of **displacement** (in cm) as a function of time (in s) is shown above. What are the **period** and **amplitude** of this simple harmonic motion?

- A) $T = 1\text{s}$, $A = 2\text{cm}$
- B) $T = 2\text{s}$, $A = 2\text{cm}$
- C) $T = 4\text{s}$, $A = 2\text{cm}$
- D) $T = 2\text{s}$, $A = 1\text{cm}$
- E) $T = 4\text{s}$, $A = 1\text{cm}$

EXTRA: what is ω ?



$$x(t) = A \cos(\omega t + \phi)$$

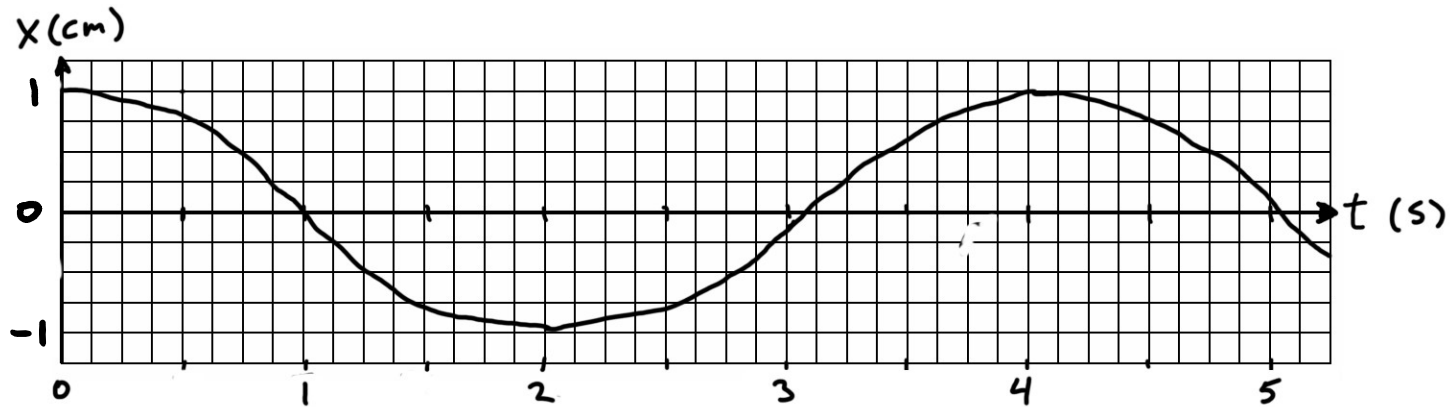
$$A = 1 \text{ cm}$$

$$T = 4 \text{ s}$$

A plot of **displacement** (in cm) as a function of time (in s) is shown above. What are the **period** and **amplitude** of this simple harmonic motion?

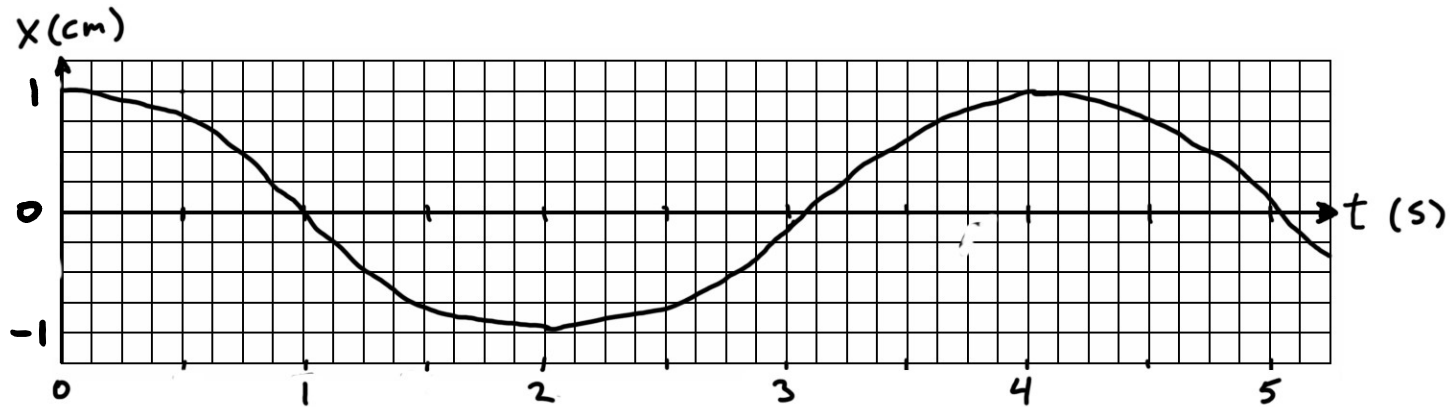
- A) $T = 1 \text{ s}$, $A = 2 \text{ cm}$
- B) $T = 2 \text{ s}$, $A = 2 \text{ cm}$
- C) $T = 4 \text{ s}$, $A = 2 \text{ cm}$
- D) $T = 2 \text{ s}$, $A = 1 \text{ cm}$
- E) $T = 4 \text{ s}$, $A = 1 \text{ cm}$

EXTRA: what is ω ?



A plot of **displacement** (in cm) as a function of time (in s) is shown above. Which function below describes this motion?

- A) $x(t) = \cos(t)$
- B) $x(t) = \cos(4t)$
- C) $x(t) = \cos(2\pi t)$
- D) $x(t) = \cos(\pi t)$
- E) $x(t) = \cos(\pi/2 t)$



A plot of **displacement** (in cm) as a function of time (in s) is shown above. Which function below describes this motion?

- A) $x(t) = \cos(t)$
- B) $x(t) = \cos(4t)$
- C) $x(t) = \cos(2\pi t)$
- D) $x(t) = \cos(\pi t)$
- E) $x(t) = \cos(\pi/2 t)$

period of \cos is 2π
 graph is $\cos(\omega t)$: when $t=4s$,
 graph goes back to 1, so must
 have $\omega t = 2\pi$ here.

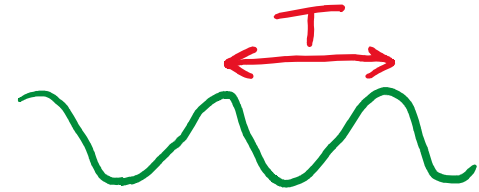
$$\omega = \frac{2\pi}{4s} = \frac{\pi}{2} s^{-1}$$

FREQUENCY & PERIOD

angular
frequency

$$x(t) = A \cos(\omega t + \phi)$$

Period T : time from max \rightarrow max



$$T = \frac{2\pi}{\omega} \quad \text{since cos repeats every } 2\pi.$$

Frequency f : oscillations per time $f = \frac{1}{T}$

$$\text{gives: } \omega = 2\pi f$$