

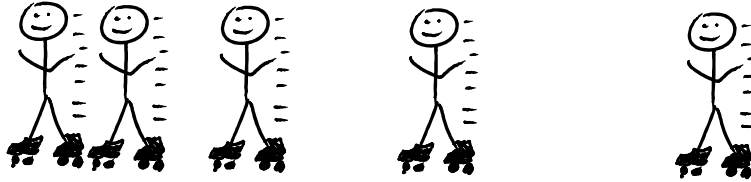
PHYSICS:

Our goal: - observe the universe
- figure out the rules
(represent by mathematical model)

Start simple: rules for motion + interaction of solid objects → Need to represent motion mathematically

Exercise: make a motion diagram

e.g. object moving across surface w. friction



Particle model

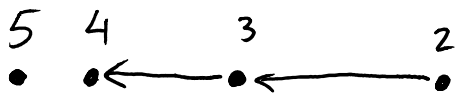


(average) velocity between 2 and 3:

$$\vec{V} = \frac{\Delta \vec{r}}{\Delta t}$$

→ vector from initial point to final point

→ time elapsed

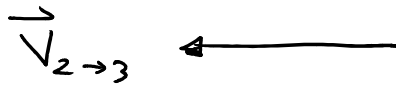


Acceleration:

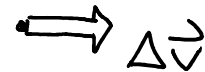
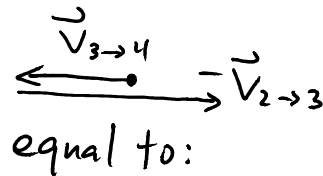
$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t}$$

! difference between velocity vectors (later minus earlier)
 ← time step

e.g. acceleration at point 3:



$$\Delta \vec{v} \approx \vec{v}_{3 \to 4} - \vec{v}_{2 \to 3}$$



Acceleration is to the right.

Q: What was the POSITION of the object at the chosen time?

Need to introduce coordinates to describe locations of objects.

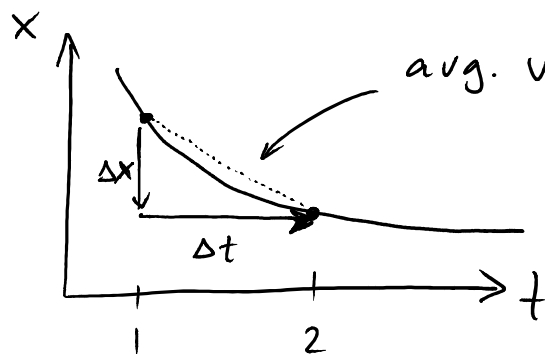
CHOOSE $x=y=z=0$ point

CHOOSE $+x$ direction, $+y$ direction

→ velocities, lengths, accelerations don't depend on our choices

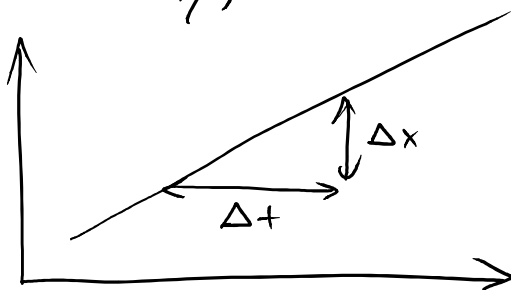
Represent motion of objects by $(x(t), y(t), z(t))$

Represent visually via graph:

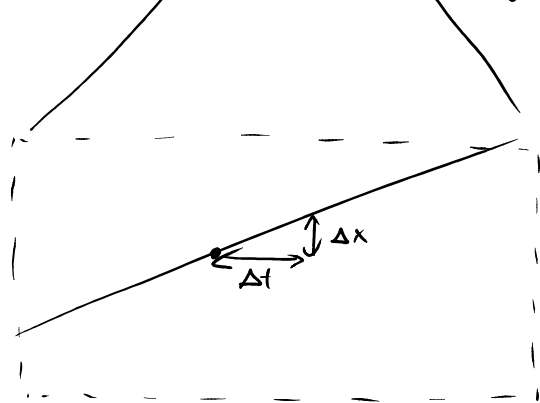
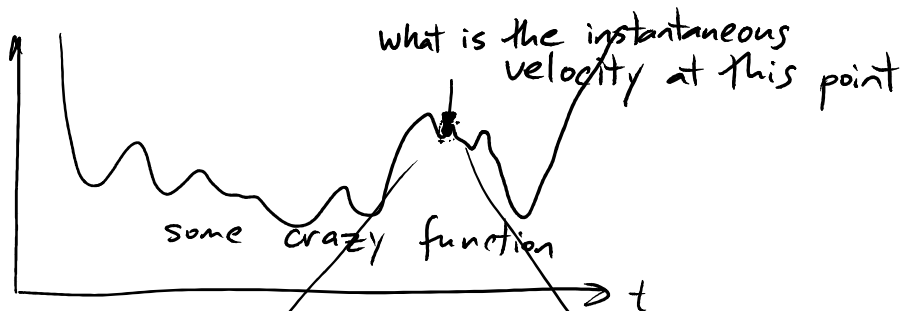


$$\frac{\Delta x}{\Delta t} = \text{slope of dotted segment}$$

Uniform motion:
(constant velocity)



$$\frac{\Delta x}{\Delta t} \text{ same for any } \Delta t$$



any smooth function looks like a straight line if we zoom in enough

∴ define v as the slope of this line

$$V_x = \lim_{\Delta t \rightarrow 0} \frac{\Delta x}{\Delta t} \equiv \frac{dx}{dt} \quad \text{DERIVATIVE OF } x(t)$$

↑ defined as